



JPL

Near real-time estimates of the mixing of oil and seawater using polarimetric SAR

Brent Minchew¹

Cathleen Jones²

Ben Holt²

¹Caltech

²JPL



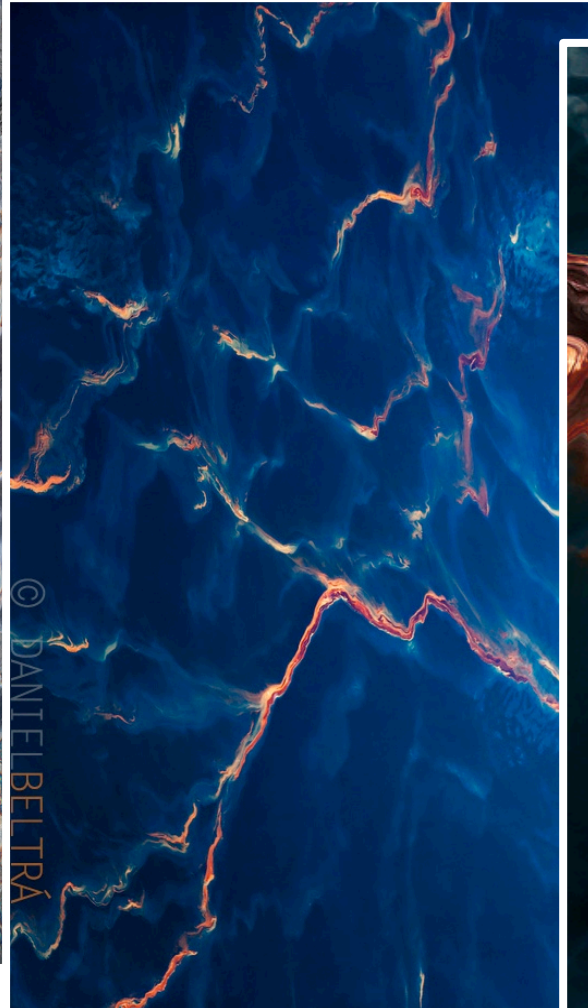
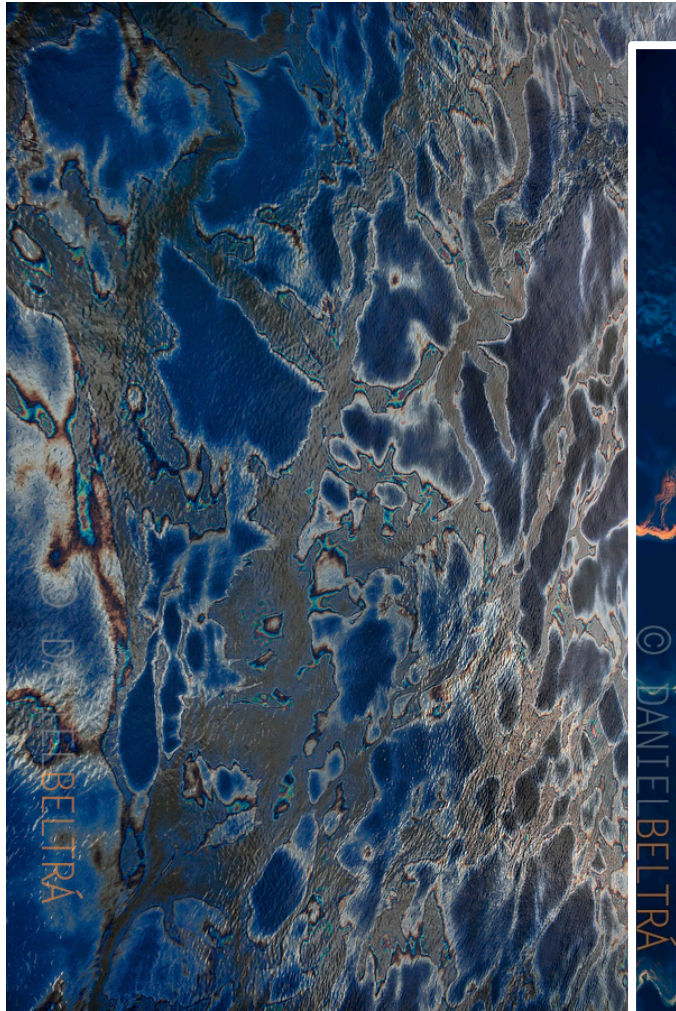
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Understanding the problem

- ◆ The environmental impact of oil depends on:
 - Type and quantity of oil spilled
 - Properties as a function of time
 - Organisms and environments exposed
 - Nature of the exposure
- ◆ Response methods have a time window:
 - Type and quantity of oil
 - Initial spill conditions
 - Weathering and emulsion rates
 - Type of environments that will be affected

Source: NOAA

Oil on the sea surface



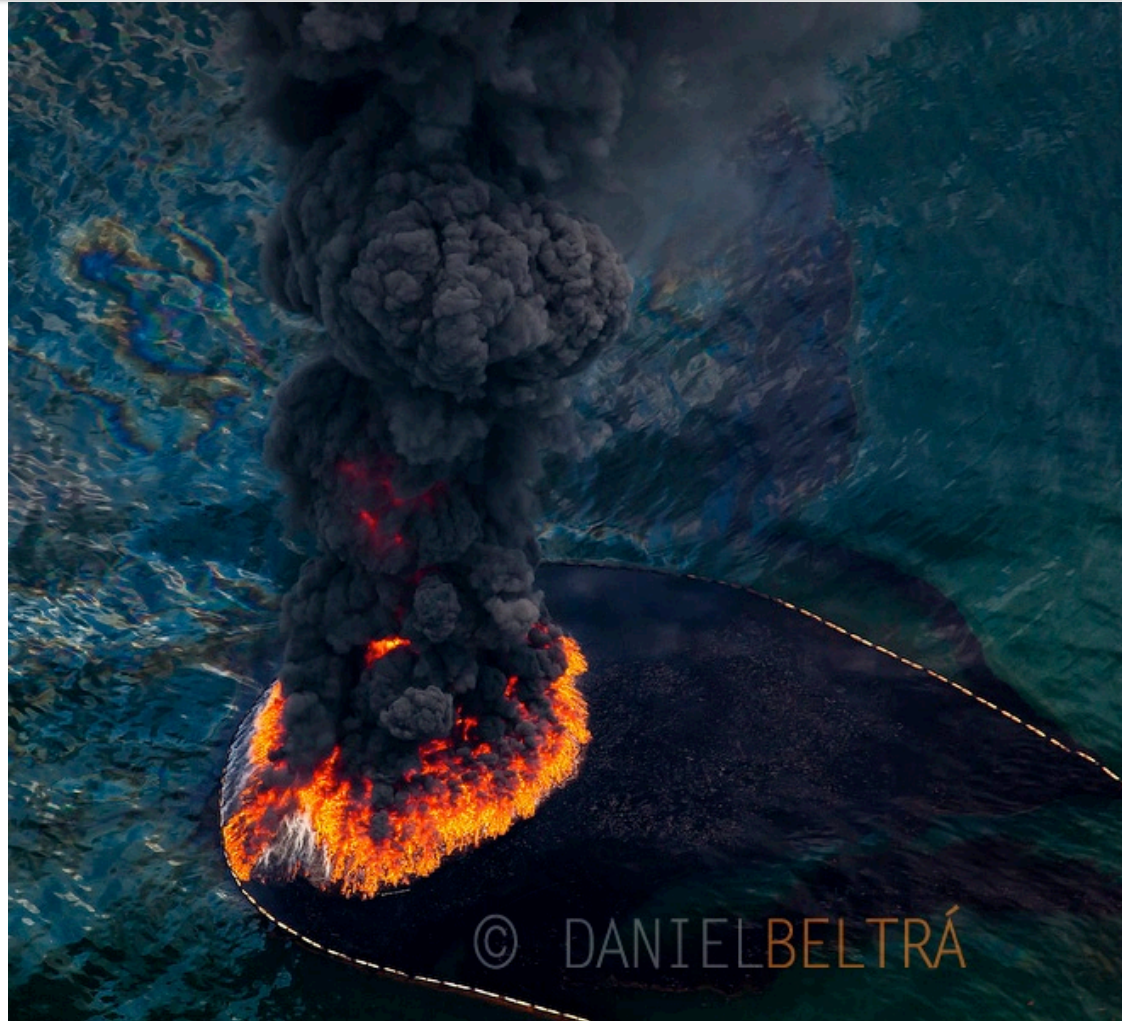
Cleanup methods



Mechanical: Booms, skimmers, vacuums, etc.

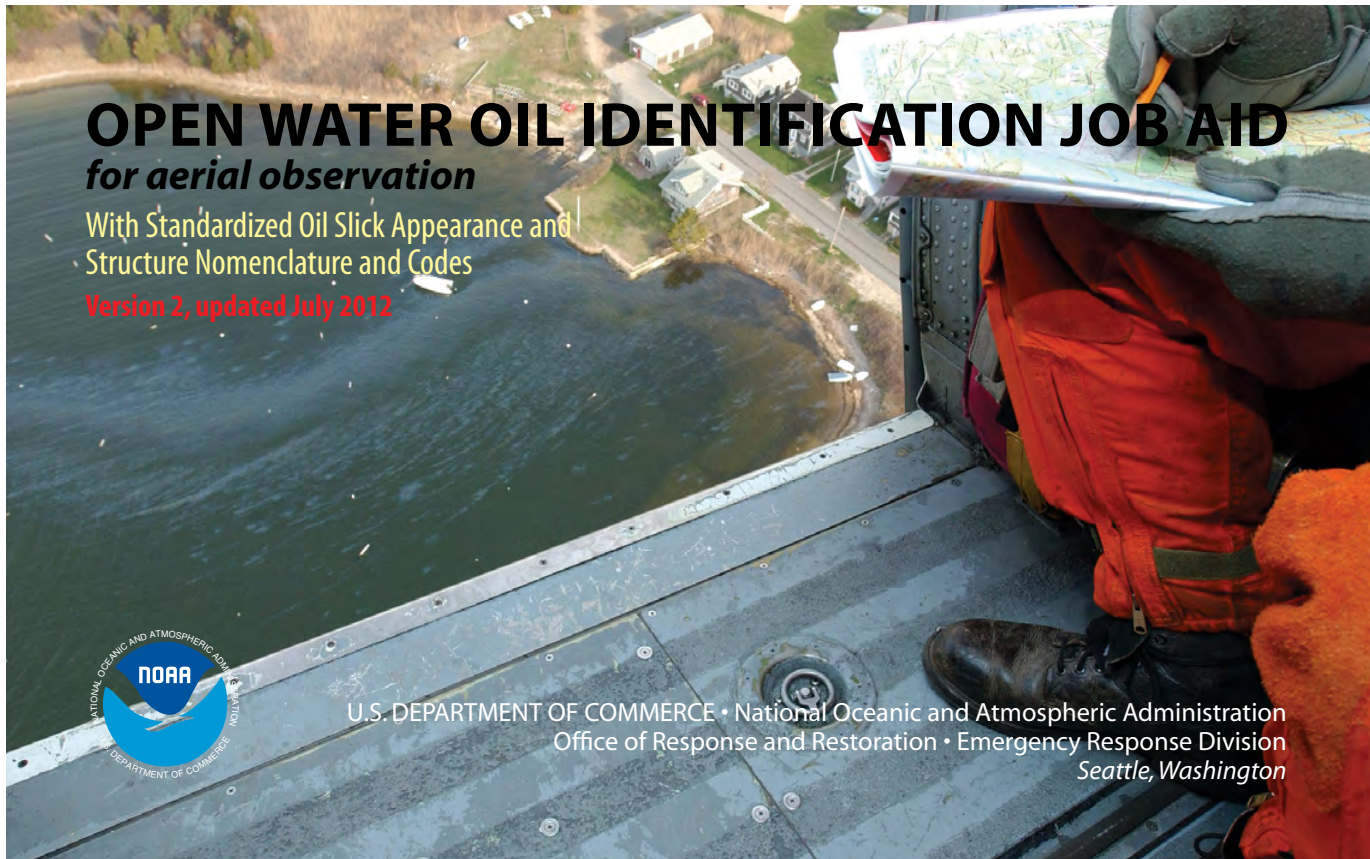
Cleanup methods

Chemical dispersants



In situ burning

Observational strategy



Limitations:

Must be done during the day

Can only be done in good weather

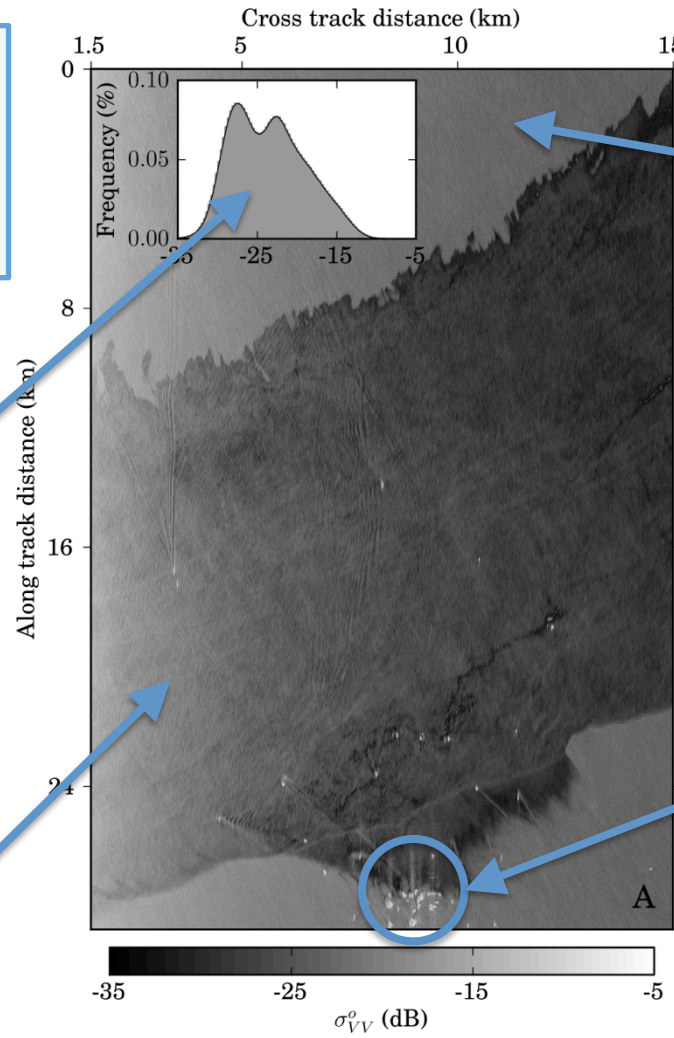
Based on skills and interpretation of the observer

Observing oil with radar

- UAVSAR VV power
- Collected June 2010
- Approximately 24 hours of flow from the well

Bimodal histogram

Oil on or near the surface = low backscatter power



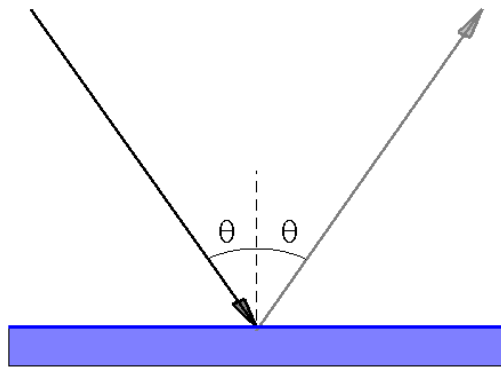
Relatively clean water

Deepwater Horizon site

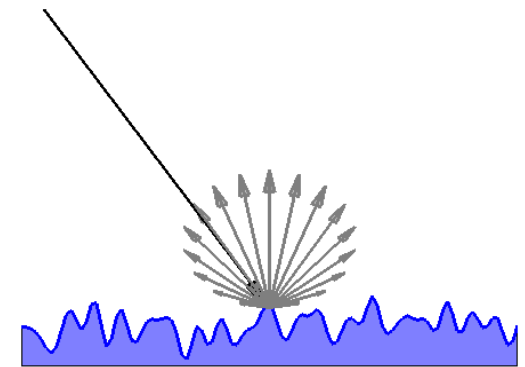
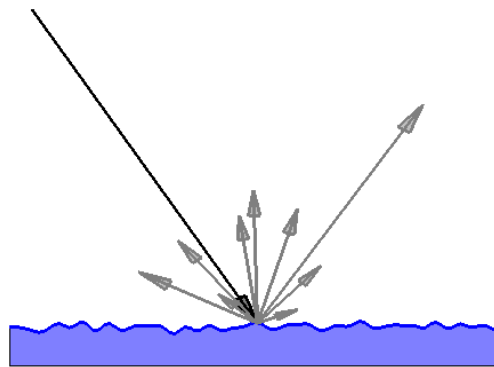
How it works

2 ways for oil to reduce radar backscatter power:

- Smoothing surface roughness (decreasing surface tension)



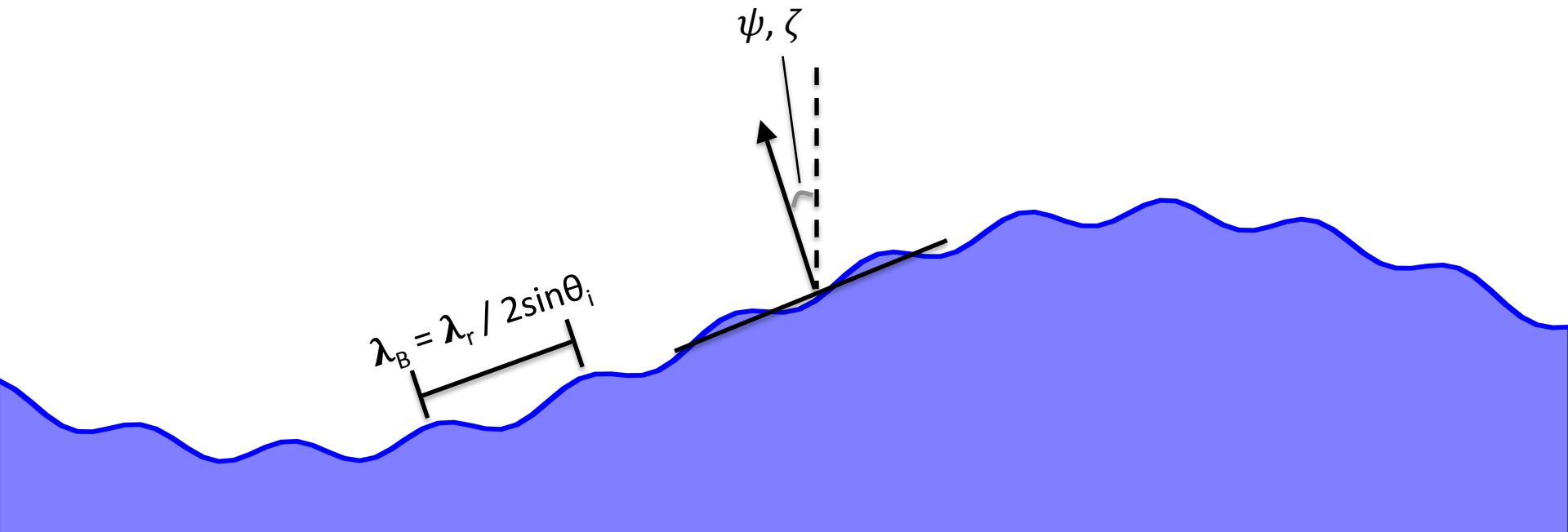
perfectly
smooth



perfectly
rough

- Reducing total scattered power (only when mixed)

Modeling sea clutter



- Tilted Bragg or small perturbation model
- Scattering is due to waves $\rightarrow k_B = 2k_r \sin \theta_i$
- Small scale roughness is tilted by long wavelength waves
- Oil only affects small scale roughness

Expanded capability: PolSAR

$$\sigma_{pp}^o = (4\pi k_r^4 \cos^4 \theta_i) \Gamma_{pp} W$$

- ◆ Reflectivity is polarization dependent

$$\Gamma_{pp} = \Gamma_{pp}(\varepsilon_r, \psi, \zeta)$$

- ◆ Roughness is polarization independent

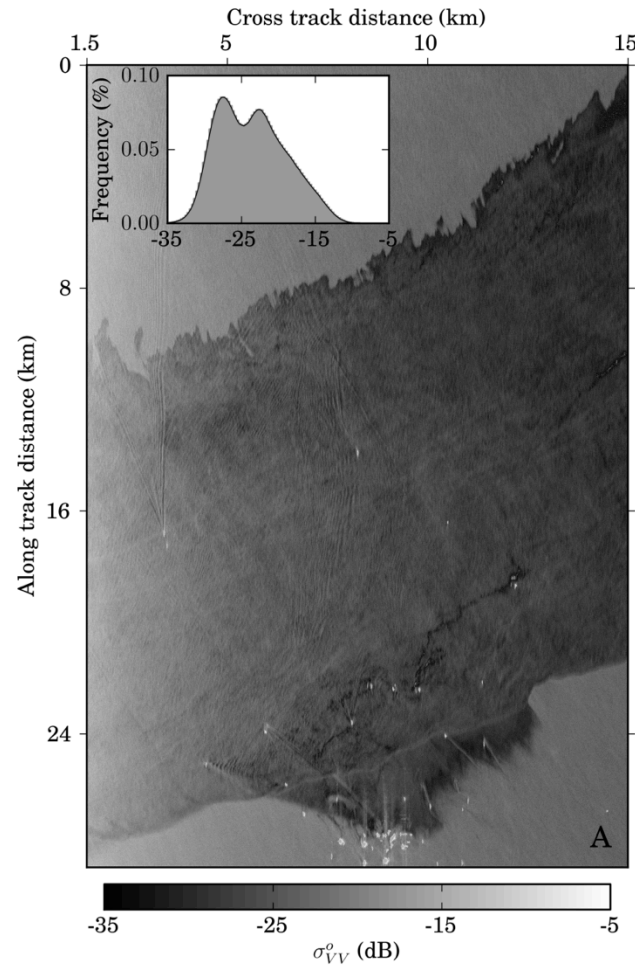
$$W = W(h_B, \ell_B, \psi, \zeta)$$

Meeting a need

- ◆ Need: Collect data on oil properties
- ◆ Assume: Binary oil/water classification is a solved problem
- ◆ Goal: Distinguish mixed oil from thin films
- ◆ Connect radar-derived characteristics with standard optical classification systems

Inferring oil properties

- Step 0: Mask relatively clean water

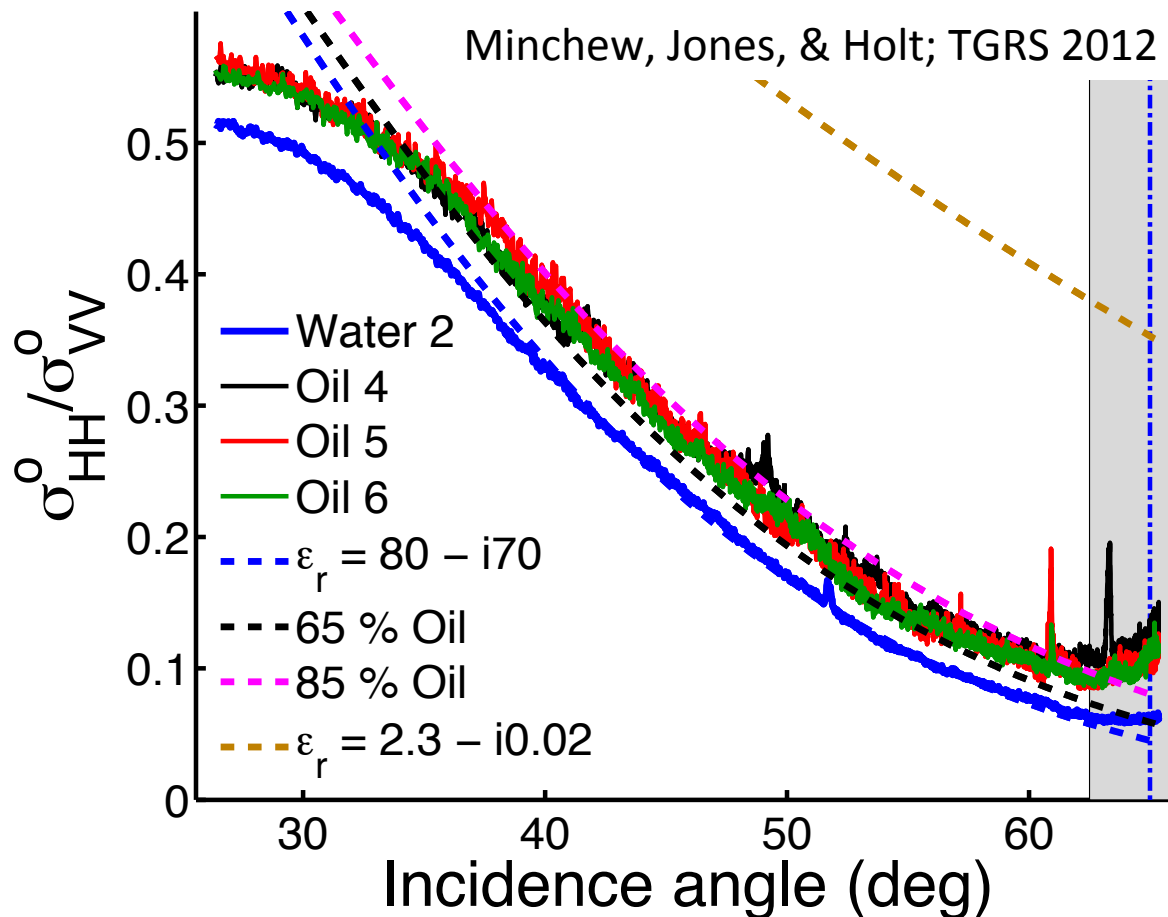


Inferring oil properties

- Step 1: Estimate surface slope (long wavelength)

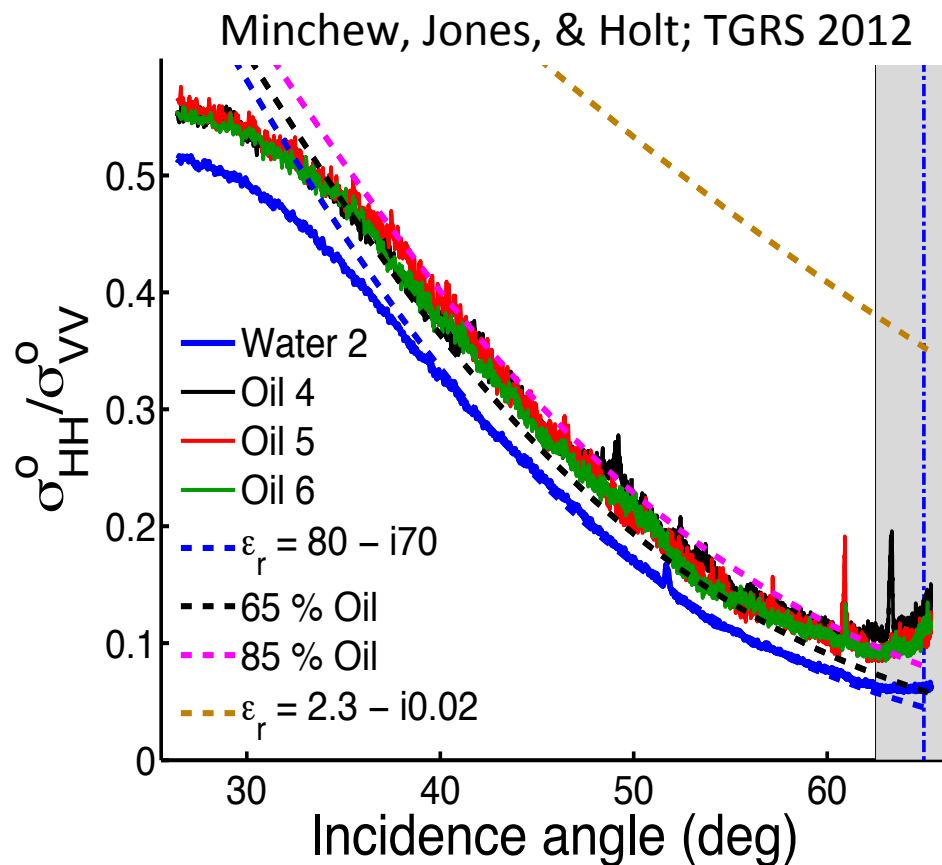
$$\frac{\sigma_{HH}^o}{\sigma_{VV}^o} = \frac{\Gamma_{HH}}{\Gamma_{VV}}$$

$$\Gamma_{pp} = \Gamma_{pp}(\epsilon_r, \psi, \zeta)$$



Inferring oil properties

Step 2: Find oil weighting factor



$$\frac{\sigma_{HH}^o}{\sigma_{VV}^o} = \frac{\Gamma_{HH}}{\Gamma_{VV}}$$

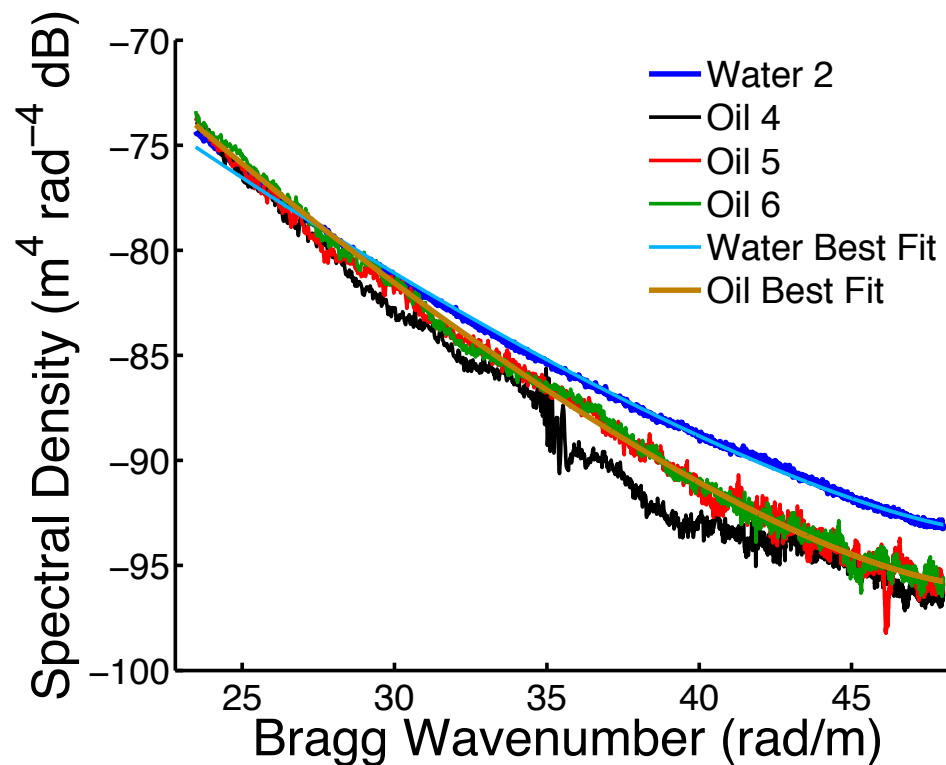
$$\Gamma_{pp} = \Gamma_{pp}(\epsilon_r, \psi, \zeta)$$

$$\epsilon_r = w_o \epsilon_r^{oil} + (1 - w_o) \epsilon_r^{water}$$

Inferring oil properties

Step 3: Calculate roughness spectrum

$$W = \frac{\sigma_{VV}^o}{(4\pi k_r^4 \cos^4 \theta_i) \Gamma_{VV}}$$



Minchew, Jones, & Holt; TGRS 2012

Inferring oil properties

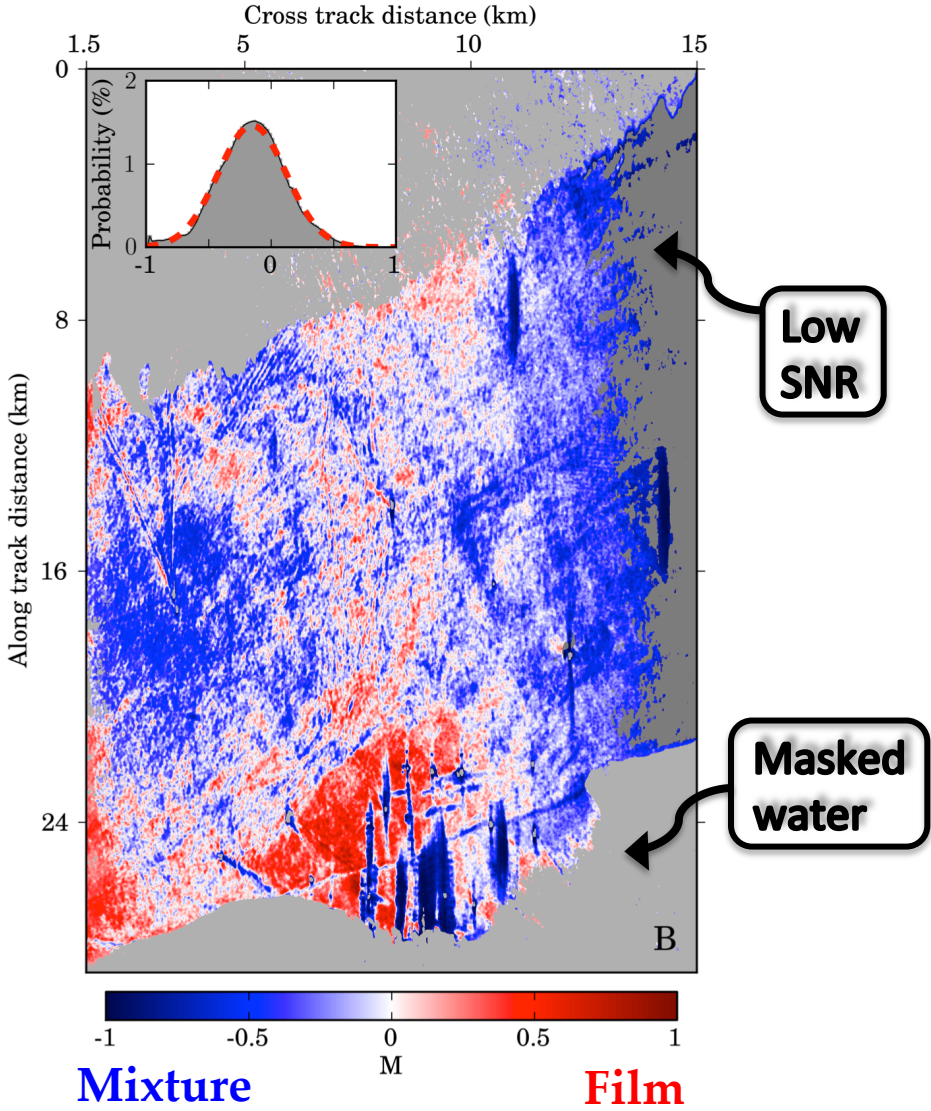
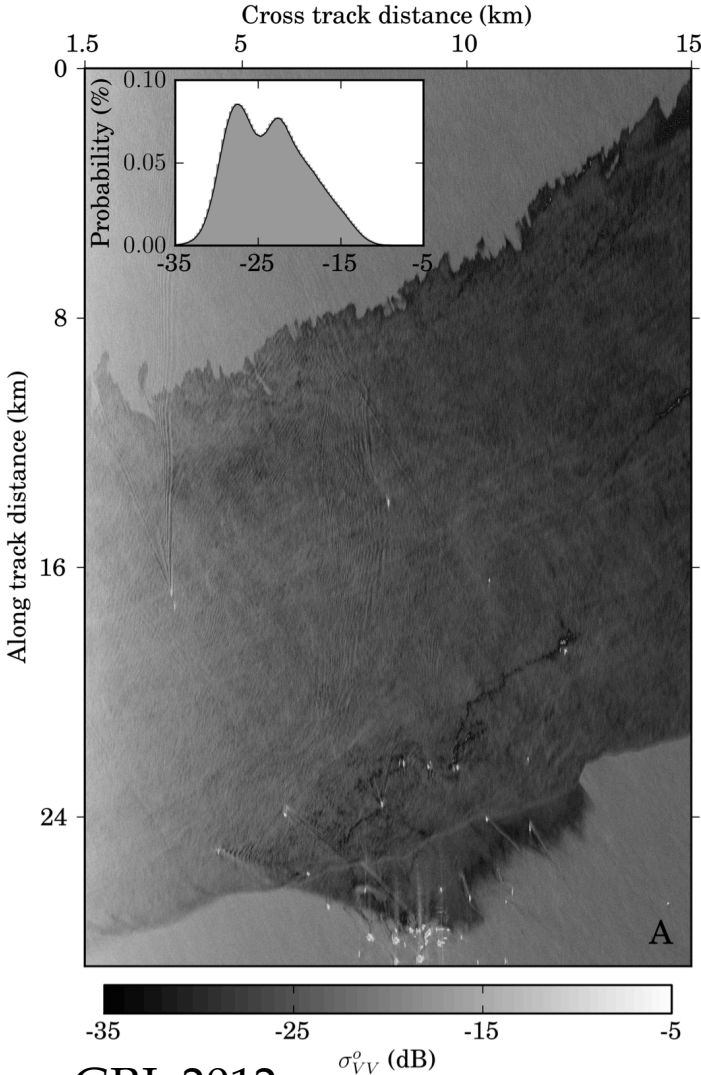
Step 4: Oil/water mixing index

$$M = \frac{1}{\sigma_{VV}^{o(water)}} \left[\frac{\partial \sigma_{VV}^o}{\partial W} \Delta W - \frac{\partial \sigma_{VV}^o}{\partial \Gamma_{VV}} \Delta \Gamma_{VV} \right]$$
$$\approx \frac{W^{water} - W^{oil}}{W^{water}} - \frac{|\alpha_{VV}^{water}|^2 - |\alpha_{VV}^{oil}|^2}{|\alpha_{VV}^{water}|^2}$$

fully mixed $-1 \leq M \leq 1$ thin film

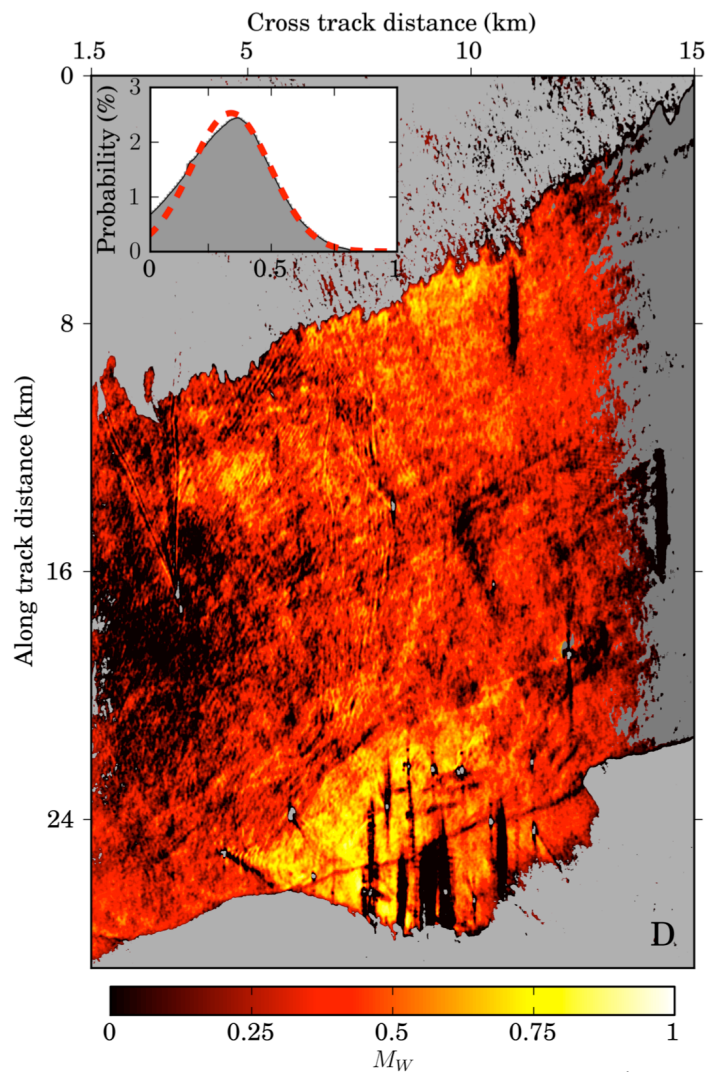
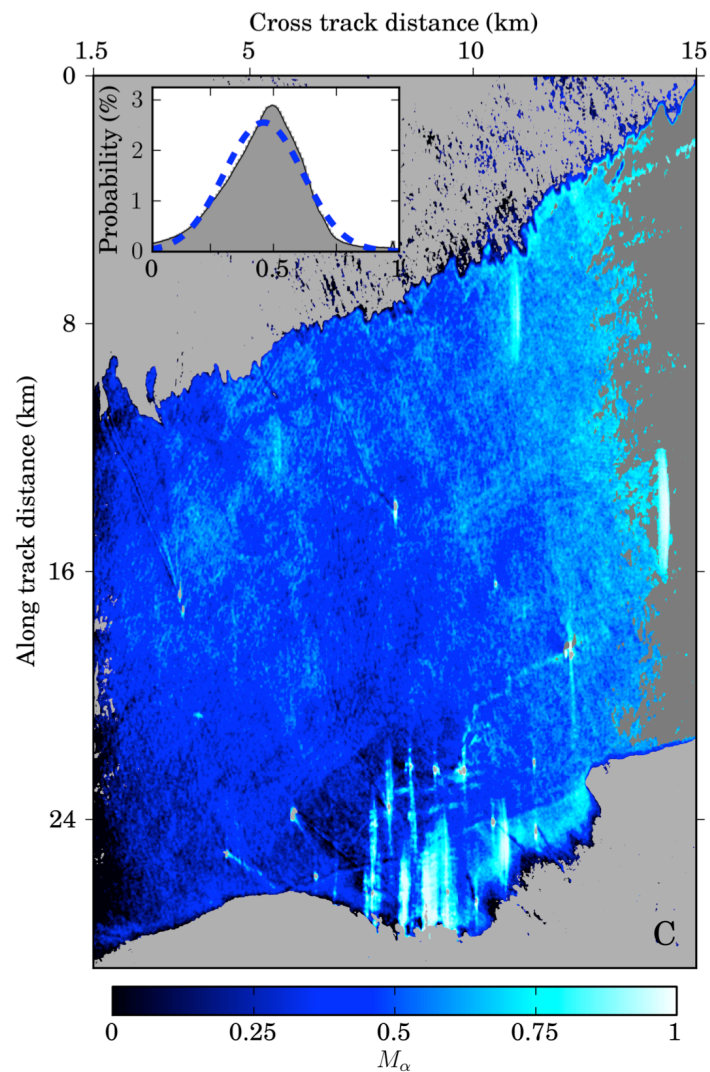
$$\alpha_{VV} = \frac{(\varepsilon_r - 1) \{ \sin^2 \theta_i - \varepsilon_r [1 + \sin^2 \theta_i] \}}{(\varepsilon_r \cos \theta_i + \sqrt{\varepsilon_r - \sin^2 \theta_i})^2}$$

Results



Minchew, GRL 2012

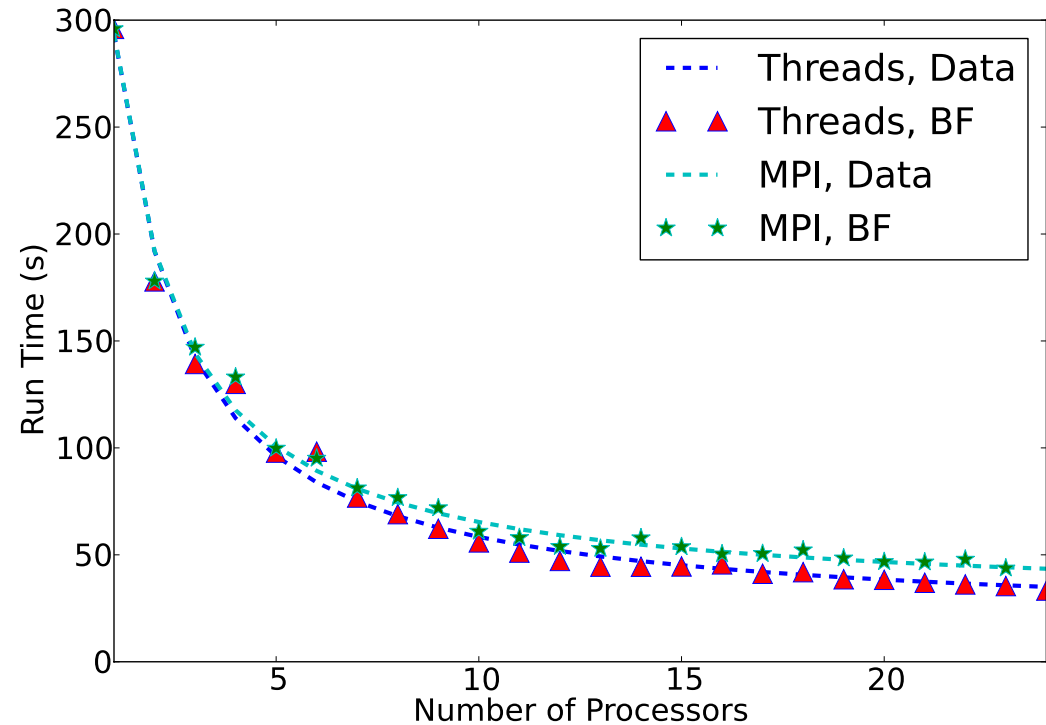
Results



Minchew, GRL 2012

Implementation

- ◆ Mdex: software suite implemented in C++ with Python bindings (Minchew)
- ◆ ‘Hybrid’ parallelization
 - Distributed memory: OpenMPI
 - Shared memory: POSIX threads
- ◆ Standard libraries
- ◆ Some human interface



Readiness

- ◆ Beyond binary
- ◆ PolSAR → oil properties
- ◆ Existing classification system
- ◆ Can be done in near real-time

Questions?



Thanks: Cathleen Jones, Ben Holt, and the entire UAVSAR team
Daniel Beltá and Susan Newbold
Mark Simons